

Differential Geometry I: Exercises

University of Regensburg, Winter Term 2023/24

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Please hand in the exercises until **Tuesday, January 23**

12 noon in the letterbox of your group (no. 15 or 16)



Exercise Sheet no. 12

1. Exercise (4 points).

Let (M^2, g) be a two-dimensional Riemannian submanifold of \mathbb{R}^3 . We call M a *minimal surface* if the mean curvature of M in \mathbb{R}^3 vanishes.

- Show that a minimal surface has non-positive sectional curvature, and if the sectional curvature is 0 in $p \in M$, then the fundamental form vanishes in p .
- Consider the *catenoid*

$$\begin{aligned} \Phi_1: \mathbb{R}^2 &\rightarrow \mathbb{R}^3 \\ (x, y) &\mapsto \begin{pmatrix} \alpha \cosh(x) \cos(y) \\ \alpha \cosh(x) \sin(y) \\ \sinh(x) \end{pmatrix} \end{aligned}$$

and the *helicoid*

$$\begin{aligned} \Phi_2: \mathbb{R}^2 &\rightarrow \mathbb{R}^3 \\ (x, y) &\mapsto \begin{pmatrix} x \cos(y) \\ x \sin(y) \\ \beta y \end{pmatrix} \end{aligned}$$

with constants $\alpha, \beta \in \mathbb{R}$. Compute the induced metrics g_1, g_2 on \mathbb{R}^2 and the Weingarten maps. Show that the catenoid and the helicoid are minimal surfaces in \mathbb{R}^3 .

- Compute the sectional curvatures of both surfaces. Does there exist an isometry $\phi: (\mathbb{R}^2, g_1) \rightarrow (\mathbb{R}^2, g_2)$?
- Show that there does not exist an isometry $\bar{\phi}: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ such that $\bar{\phi}(\text{image}(\Phi_1)) = \text{image}(\Phi_2)$ holds.

2. Exercise (4 points).

Let (M^n, g) be a Riemannian manifold with non-positive sectional curvature, i.e. $K \leq 0$. We denote by J a Jacobi field along a geodesic c of (M, g) .

- Show that $g(J, \frac{\nabla^2}{dt^2} J)$ is a non-negative function.
- Show that $\frac{d^2}{dt^2}(g(J, J))$ is a non-negative function.
- Conclude from the previous statements that the Jacobi field vanishes identically or has at most one point where it vanishes.

3. Exercise (4 points).

Let (M, g) be a semi-Riemannian manifold and J be a Jacobi field along a geodesic $c: I = [a, b] \rightarrow M$. Show that there exists a geodesic variation $c_\bullet: (-\epsilon, \epsilon) \times I \rightarrow M$ of c such that $J = \frac{d}{ds}|_{s=0} c_s$ holds.

Hint: For some $t_0 \in [a, b]$ choose a curve $\gamma: (-\epsilon, \epsilon) \rightarrow M$ with $\gamma(0) = c(t_0)$ and $\dot{\gamma}(0) = J(t_0)$. Find a vector field X along γ such that $(s, t) \mapsto c_s(t) = \exp_{\gamma(s)}(tX(s))$ is a suitable geodesic variation.

4. Exercise (4 points).

Let (M, g) be a semi-Riemannian manifold.

- a) Recall that we denote the parallel transport along a curve γ by \mathcal{P}_γ . Let $F: \mathbb{R}^2 \rightarrow M$ be a smooth map and denote by γ_t the curve in M which is given by

$$\gamma_t(s) = \begin{cases} F(4st, 0) & s \in [0, \frac{1}{4}] \\ F(t, t(4s-1)) & s \in [\frac{1}{4}, \frac{1}{2}] \\ F(t(3-4s), t) & s \in [\frac{1}{2}, \frac{3}{4}] \\ F(0, t(4-4s)) & s \in [\frac{3}{4}, 1], \end{cases}$$

i.e. the piecewise smooth curve which gives the image of the closed polygonal chain with corner points $(0, 0)$, $(t, 0)$, (t, t) and $(0, t)$. Show that

$$\lim_{t \rightarrow 0} \frac{\mathcal{P}_{\gamma_t} v - v}{t^2} = R\left(\frac{\partial F}{\partial x_2}(0), \frac{\partial F}{\partial x_2}(0)\right)v$$

holds for all $v \in T_{F(0,0)}M$.

Hint: Use the following statement from the lecture (Lemma V.4.2): Let $\alpha: \mathbb{R}^2 \rightarrow M$ be a smooth map and X a vector field along α such that $\frac{\nabla}{\partial x} X = \frac{\nabla}{\partial y} X$ holds, then we have

$$\frac{\nabla}{\partial x} \frac{\nabla}{\partial x} X - \frac{\nabla}{\partial y} \frac{\nabla}{\partial y} X = R\left(\frac{\partial \alpha}{\partial x}, \frac{\partial \alpha}{\partial y}\right)X.$$

- b) If (M, g) is flat, then for every point $p \in M$ and vector $v \in T_p M$, there exists an open neighbourhood of p given by $U \subset M$ and a section $X: U \rightarrow TM$ of the tangent bundle TM , which is parallel, i.e. $\nabla X = 0$ on U , and satisfies $X_p = v$. Construct a counterexample in the non-flat case for the previous statement.