

Lemma 2.43

Let $P \subset M$ be a spacelike submfd of a Lorentzian mfd, and $c = [0, b] \rightarrow M$

a lightlike geodesic with $c(0) =: p \in \underline{P}$,

but $\dot{c}(0) \notin N_p P$. Then in every nbhd of c

we find a timelike curve from \underline{P} to $q := c(b)$.

Proof: There is $X_0 \in T_p \underline{P}$ with $\langle X_0, \dot{c}(0) \rangle > 0$.

Define $X \in \Gamma(c^* TM)$ by $X(0) = X_0$, $\frac{\nabla}{dt} X = 0$.

Define $V(t) := \left(1 - \frac{t}{b}\right) X(t) \Rightarrow V(0) = X_0, V(b) = 0$

Choose a variation c_s of c with $\frac{\partial c_s}{\partial s} \Big|_{s=0} = V$,

$c_s(0) \in \underline{P}$ and $c_s(b) = q$ for all s .

c lightlike $\Rightarrow \langle \dot{c}_s, \dot{c}_s \rangle \Big|_{s=0} = 0$

$$\frac{\partial}{\partial s} \langle \dot{c}_s, \dot{c}_s \rangle \Big|_{s=0} = 2 \left\langle \frac{\partial}{\partial s} \frac{\partial c_s}{\partial t}, \dot{c}_s \right\rangle \Big|_{s=0} = 2 \left\langle \frac{\nabla}{dt} V, \dot{c} \right\rangle$$

$$= -\frac{2}{5} \langle X, \dot{c} \rangle = -\frac{2}{6} \langle X(4), \dot{c}(4) \rangle < 0$$

$$\Rightarrow \exists s_0 > 0 \forall s \in (0, s_0)$$

c_s is timelike

□

Theorem 2.44

Let M be a Lorentzian mfd, $P \subset M$ spacelike submfd, and let $c: [0, b] \rightarrow M$ be a causal curve from $c(0) =: p \in P$ to $q =: c(b)$.

Then in every (compact-open) neighborhood of c there is a timelike curve from P to q , unless c is, up to parametrization, a lightlike geodesic with $\dot{c}(0) \in N_p P$ such that P has no focal values $t_0 < b$ along c .

Proof: If c is not a lightlike (pre-)geodesic, we find a timelike curve from p to q in a nbhd of c .

Thus wlog c is a light like geodesic. Use Lemma 2.43 to see that the theorem holds for $\dot{c}(0) \notin T_p P$.

Prop 2.38 gives the statement if there are no focal points values in $(0, b]$ in the case $\dot{c}(0) \in T_p P$.

Recall X ~~timelike~~ $\in TM$ $\|X\| = \sqrt{|g(X, X)|}$
 $= \sqrt{|\langle X, X \rangle|}$

For causal curves $c: [a, b] \rightarrow M$

$$L[c] = \int_a^b |\dot{c}(t)| dt$$

proper time

c parametrized by proper time

$$\Leftrightarrow g(\dot{c}(t), \dot{c}(t)) \equiv -1$$

Prop 2.44 a (First variation formula for timelike curves in Lorentzian mfd)

M a Lorentzian mfd, $c: [a, b] \rightarrow M$ a timelike smooth, parametrized by proper time. Let $c_s: [a, b] \times (-\epsilon, \epsilon) \rightarrow M$, $(t, s) \mapsto c_s(t)$ a smooth variation of c , $V(t) := \frac{\partial c_s}{\partial s}(t, 0)$.

$$\text{Then } \frac{\partial}{\partial s} \Big|_{s=0} \mathcal{L}[c_s] = \int_a^b \langle V, \nabla_{\dot{c}} \dot{c} \rangle dt + \langle V(a), \dot{c}(a) \rangle - \langle V(b), \dot{c}(b) \rangle.$$

Note: Lorentzian analogue

of Thm 3.2.8 of Clara 4th.

Proof $\frac{d}{ds} L[\dot{c}_s] = \int_a^b \frac{\partial}{\partial s} \sqrt{-\langle \dot{c}_s, \dot{c}_s \rangle} dt$

$$= \int_a^b \frac{1}{2} \frac{-2 \langle \frac{\nabla}{ds} \dot{c}_s, \dot{c}_s \rangle}{\sqrt{-\langle \dot{c}_s, \dot{c}_s \rangle}} dt$$

$$= - \int_a^b \left\langle \frac{\nabla}{dt} \frac{\partial c_s}{\partial s}, \frac{\dot{c}_s}{|\dot{c}_s|} \right\rangle dt \quad s=0$$

$$= - \int_a^b \left\langle \frac{\nabla}{dt} V, \dot{c} \right\rangle dt$$

$$= - \underbrace{\int_a^b \frac{d}{dt} \langle V, \dot{c} \rangle dt}_{\langle V(a), \dot{c}(a) \rangle - \langle V(b), \dot{c}(b) \rangle} + \int_a^b \left\langle V, \frac{\nabla}{dt} \dot{c} \right\rangle dt$$

$$\langle V(a), \dot{c}(a) \rangle - \langle V(b), \dot{c}(b) \rangle \quad \square$$

In particular $p, q \in M$

\tilde{c} is stationary point of

$\{c$ timelike C^2 -curves

parametr. by proper time

from p to q $\} \xrightarrow{L} \mathbb{R}$

$\Leftrightarrow \tilde{c}$ is a ~~pre~~-geodesic.

Prop 2.113 (Second var. formula)

Let M, c, c_0, V as above,

$$A(s) = \frac{\nabla}{ds} \frac{\partial c_s}{\partial s} \Big|_{s=0} \in T^*(c^*TM).$$

Additionally we assume $c=c_0$
is (timelike) geodesic.

$$\text{Then } \frac{\partial^2}{\partial s^2} L[c_s] \Big|_{s=0} = \langle A(a), \dot{c}(a) \rangle -$$

$$\langle A(b), \dot{c}(b) \rangle - \int_a^b \langle R(V, \dot{c}) / V, \dot{c} \rangle dt$$

$$- \int_a^b \langle \pi^{\text{hor}} \left(\frac{\nabla V}{dt} \right), \pi^{\text{hor}} \left(\frac{\nabla V}{dt} \right) \rangle dt$$

Here

$$\frac{DV}{dt} = \underbrace{\pi^{\text{tan}} \left(\frac{DV}{dt} \right)}_{\in \mathbb{R} \dot{c}} + \underbrace{\pi^{\text{hor}} \left(\frac{DV}{dt} \right)}_{\perp \dot{c}}$$

$$\parallel \quad \quad \quad \perp$$

$$\frac{D}{dt} \pi^{\text{tan}}(V) \quad \quad \quad \frac{D}{dt} \pi^{\text{hor}}(V)$$

$$\frac{D}{dt} \langle V, \dot{c} \rangle = \dot{c}$$

Proof: $\frac{\partial^2}{\partial s^2} \Big|_{s=0} \mathcal{L}[c_s] =$

$$- \int_a^b \left\langle \frac{D}{ds} \frac{D}{dt} \frac{\partial c_s}{\partial s} \Big|_{s=0}, \dot{c} \right\rangle dt$$

$$- \int_a^b \left\langle \frac{D}{dt} \frac{\partial c_s}{\partial s} \Big|_{s=0}, \frac{D}{ds} \left(\frac{\dot{c}_s}{|\dot{c}_s|} \right) \Big|_{s=0} \right\rangle dt$$

$$\approx - \int_a^b \langle R(V, \dot{c}) | V, \dot{c} \rangle dt - \int_a^b \left\langle \frac{\nabla}{dt} \overbrace{\frac{\nabla}{ds} \frac{\partial c_s}{\partial s}}^A \Big|_{s=0} \dot{c} \right\rangle dt$$

$$\rightarrow \int_a^b \left\langle \frac{\nabla}{dt} V(t) \Big|_{s=0} \pi^{\text{hor}} \left(\frac{\nabla V}{dt} \right) \right\rangle dt = \text{rhs}$$

$$\text{as } \int_a^b \left\langle \frac{\nabla}{dt} A \Big|_{s=0} \dot{c} \right\rangle dt = \int_a^b \frac{d}{dt} \langle A, \dot{c} \rangle dt$$

$$= \langle A(b), \dot{c}(b) \rangle - \langle A(a), \dot{c}(a) \rangle$$

$$\frac{\nabla}{ds} \left(\frac{\dot{c}_s}{|\dot{c}_s|} \right) \Big|_{s=0} = \frac{\nabla}{ds} \Big|_{s=0} \dot{c}_s - \frac{1}{2} \frac{(-2)g \left(\frac{\nabla}{ds} \dot{c}_s, \dot{c}_s \right)}{\sqrt{-g(\dot{c}_0, \dot{c}_0)}} \dot{c}_0$$

$$= \frac{\nabla}{dt} \frac{\partial c_s}{\partial s} \Big|_{s=0} + \frac{g \left(\frac{\nabla}{dt} \frac{\partial c_s}{\partial s} \Big|_{s=0}, \dot{c} \right)}{1} \dot{c}$$

$$\frac{\nabla}{dt} V \Big|_{s=0} = \frac{\nabla}{dt} V + \left\langle \frac{\nabla}{dt} V, \dot{c} \right\rangle \dot{c} = \pi^{\text{hor}} \left(\frac{\nabla V}{dt} \right)$$

3.2.5 Cauchy hypersurfaces

M a connected, time-oriented Lorentzian mfd.

Def 2.62

$A \subset M$ is achronal if there are no $p, q \in A$ with $p \ll q$ (i.e. no time like curve hits A at least twice)

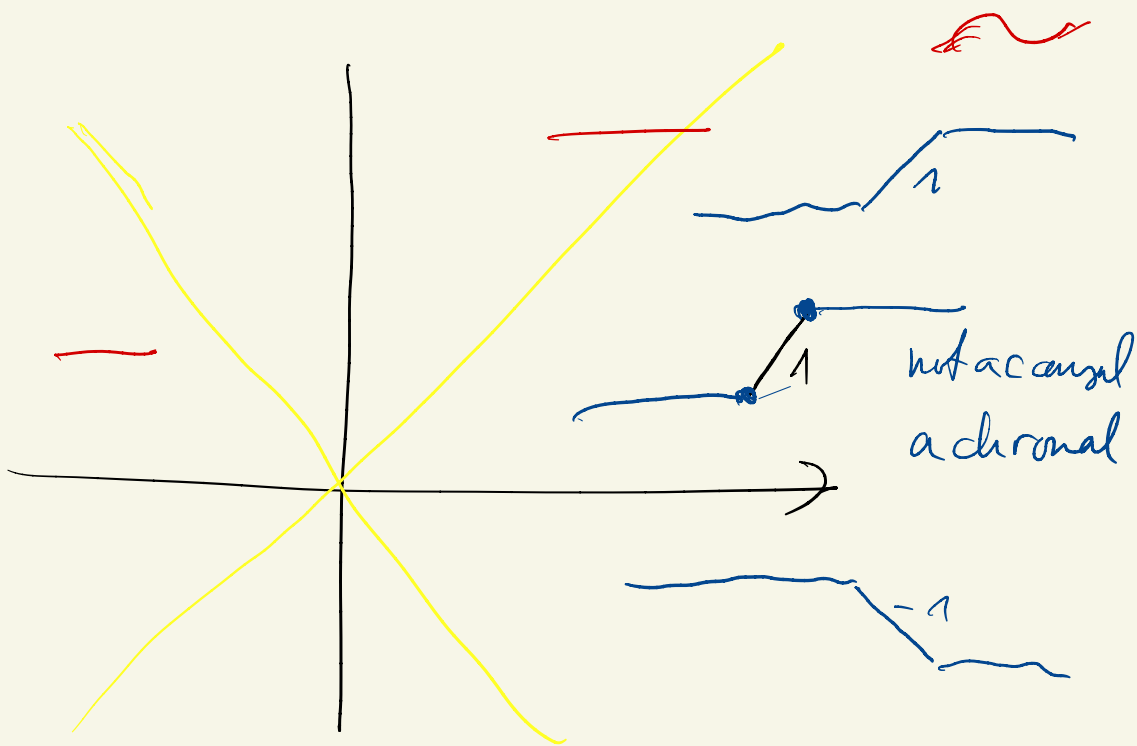
$A \subset M$ is causal if there are no $p, q \in A$ with $p < q$ (i.e. no causal curve hits A at least twice)

acausal \Rightarrow achronal

The Def 2.62 is the same if we use smooth curves or piecewise C^1 -curves.

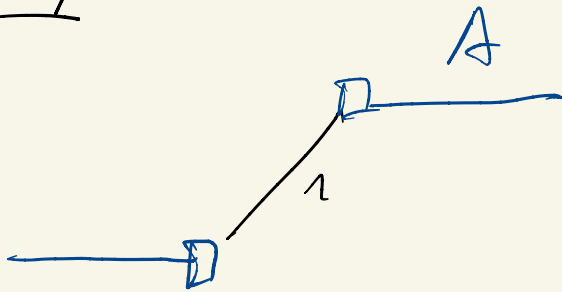
Examples $M = \mathbb{R}^{1,1}$

acausal



The closure of an achronal set
 is achronal: Suppose $p, q \in \bar{A}$
 with $p \ll q$. $\exists p_n, q_n \in A$ $p_n \rightarrow p$,
 $q_n \rightarrow q$. Prop 2.14 implies that for
 $\forall n \geq n_0$ we have $p_n \ll q_n \Rightarrow A$ not
 achronal.

Example



A acausal

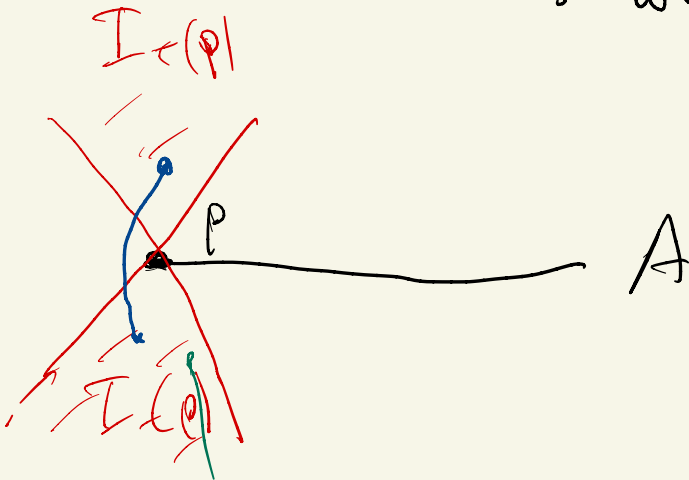
\bar{A} not acausal

Def 2.65

The edge of an achronal subset A is defined as

$$\text{edge}(A) = \left\{ p \in \bar{A} \mid \begin{array}{l} \text{for all open nbhds } U \text{ of } p \text{ there is a} \\ \text{timelike (future-directed)} \\ \text{piecewise } C^1 \text{-curve in } U \\ \text{from } I_{-\epsilon}^U(p) \text{ to } I_{+\epsilon}^U(p) \\ \text{which does not hit } A. \end{array} \right\}$$

$\mathbb{R}^{n,1}$



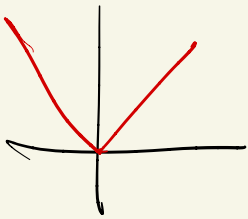
There are no such past-directed curves as this would contradict achronality, so we could replace future directed, by future-or-past-directed curves.

Example 2.66 $M = \mathbb{R}^{n,1}$

2. | a |

$$A = \left\{ \begin{pmatrix} t \\ x \end{pmatrix} \mid t = |x| \right\} =: C_{\pm}(o)$$

future light cone

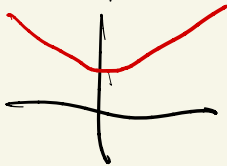


achronal, not a causal edge $(A) = \emptyset$.

2. | b |

$$A = \left\{ \begin{pmatrix} t \\ x \end{pmatrix} \mid t^2 = |x|^2 + 1 \right\}$$

acausal



edge $(A) = \emptyset$

$$2) B \subset \mathbb{R}^n, A := \{0\} \times B \subset \mathbb{R}^{n+1}$$

then $\text{edge } |A| = \{0\} \times \partial B$.

