

Scalar curvature rigidity of Einstein manifolds

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Motivation: Witten's proof of the PMT and rigidity

- (M, g) asymptotically Euclidean, spin, $\text{scal}^g \geq 0$.
- Dirac operator D on spinors, Schrödinger-Lichnerowicz formula

$$D^2 = \nabla^* \nabla + \frac{1}{4} \text{scal}.$$

- Euclidean metric δ on \mathbb{R}^n has parallel spinors ϕ_0 .
- Solve for ϕ with $D^g \phi = 0$, $\phi - \phi_0 \rightarrow 0$ at ∞ .
- Integrated S-L:

$$\int_M \left(|\nabla \phi|^2 + \frac{1}{4} \text{scal} |\phi|^2 - |D\phi|^2 \right) dV = \int_{S_\infty} Q(\phi) dS = \text{mass of } (M, g)$$

- $\Rightarrow \text{mass} \geq 0$ and $= 0$ only if ϕ is parallel, that is if g is Euclidean.
- In particular, $g = \delta$ outside compact $\Rightarrow g = \delta$ everywhere.

Scalar curvature rigidity

- $\Rightarrow (\mathbb{R}^n, \delta)$ is *scalar curvature rigid*: it is not possible to change the metric $\delta \rightsquigarrow g$ on a compact set so that $\text{scal}^g \geq \text{scal}^\delta$ everywhere and $\text{scal}^g > \text{scal}^\delta$ somewhere.
- The “Geroch conjecture” for (\mathbb{R}^n, δ) .
- Which manifolds are SCR?
- First variation of scalar curvature

$$D_g \text{scal}(h) = \left. \frac{d}{dt} \text{scal}^{g+th} \right|_{t=0} = \Delta \text{tr } h + \delta(\delta h) - \langle \text{Ric}, h \rangle.$$

- \Rightarrow Which Einstein/Ricci-flat manifolds are SCR?
- \Rightarrow Which complete, non-compact, Ricci-flat manifolds are SCR?

Gravitational instantons

- *Gravitational instanton*: complete, non-compact, Ricci-flat manifold
- Many examples in $\dim = 4$.
Asymptotic geometries AE, ALE, AF, ALF, ALG, ALH \sim volume growth at ∞ .
- Hyperkähler examples, with parallel spinors:
 - Taub-NUT
 - Gibbons-Hawking
 - Eguchi-Hanson
 - ...

Complete classification: Kronheimer, Minerbe, Chen-Chen.

- Generalize Witten's argument:
SCR for instantons with parallel spinors, D.: ALE, Hein: Taub-NUT

- Examples with no parallel spinors:
 - Riemannian Schwarzschild (/Kerr)

$$g^{RS} = \left(1 - \frac{2m}{r}\right) dt^2 + \left(1 - \frac{2m}{r}\right)^{-1} dr^2 + r^2 \sigma,$$

on $S^1(8\pi m) \times (2m, \infty) \times S^2 \rightsquigarrow S^2 \times \mathbb{R}^2$.

- Taub-Bolt

$$g^{TB} = \frac{r^2 - m^2}{r^2 - \frac{5}{2}mr + m^2} dr^2 + (r^2 - m^2)(\sigma_1^2 + \sigma_2^2) + 4m^2 \frac{r^2 - \frac{5}{2}mr + m^2}{r^2 - m^2} \sigma_3^2,$$

on $(2m, \infty) \times S^3 \rightsquigarrow \mathbb{C}P^2 \setminus \{\text{point}\}$.

- Chen-Teo instanton.

All with special geometry: One-sided type D/Hermitian. Classification??

Stability of Einstein manifolds

- Einstein metrics are critical points of Hilbert functional

$$g \mapsto \int \text{scal}^g dV^g$$

w.r.t. volume-preserving variations.

- TT-tensors: trace- and divergence-free 2-tensors.
- Einstein operator on 2-tensors: $\Delta_E = \nabla^* \nabla - 2\mathring{R}$, where $\mathring{R}h_{ij} = h^{kl}R_{iklj}$
- (Open) Einstein manifold is *stable* if

$$\mu_1(\Delta_E|_{TT}, M) = \inf \left\{ (\Delta_E h, h)_{L^2} \mid h \in C_c^\infty(TT), \|h\|_{L^2}^2 = 1 \right\} \geq 0$$

and *unstable* otherwise.

- Thm. (Wang, Dai-Wang-Wei): If (M, g) (compact) has parallel spinors, then it is stable. $\rightsquigarrow \Delta_E \sim (D^{T^*M})^2 \geq 0$.
- The Riemannian Schwarzschild and the Taub-Bolt metrics are unstable.

Thm 1 (D.-Kröncke)

Assume (M, g) compact Einstein with boundary, not locally a warped product. Let f_t be a 1-parameter family of smooth functions with supports in relatively compact Ω . Assume $h \neq 0$ TT-tensor with support in Ω satisfying

$$\int_M \langle \Delta_E h, h \rangle dV = -2 \int_M f_0 dV. \quad (1)$$

Then there is a family g_t of metrics with $g_0 = g$ and $\frac{d}{dt}g_t|_{t=0} = h$ such that

$$\text{scal}^{g_t} = \text{scal}^g + \frac{t^2}{2} f_t, \quad (2)$$

$$dV^{g_t} = dV^g, \quad (3)$$

and $g_t = g$ outside of Ω .

- Analogue to Kazdan-Warner trichotomy. For compact manifolds:
 - (i) Any smooth function is the scalar curvature of a smooth metric.
 - (ii) A smooth function is the scalar curvature of a smooth metric if it is either identically zero or strictly negative somewhere. In this case, any scalar-flat metric is Ricci-flat.
 - (iii) A smooth function is the scalar curvature of a smooth metric if it is strictly negative somewhere.

Dichotomy for perturbations of Einstein metrics:

- (i)' If (M, g) is linearly unstable, any C_c^∞ -function is a second order scalar curvature perturbation of a $C_c^\infty(TT)$ -perturbation of g .
- (iii)' If (M, g) is linearly stable, a C_c^∞ -function is a second order scalar curvature perturbation of a $C_c^\infty(TT)$ -perturbation of g if and only if it has negative integral.

No analogue of (ii): In the *neutrally linearly stable* case $\mu_1^D(\Delta_E, TT) = 0$, the infimum in $\mu_1^D(\Delta_E, TT)$ not realized by a C_c^∞ -tensor.

Proof: background

- Variation of scalar curvature, $\text{Ric} = \sigma g$,

$$D_g \text{scal}(h) = \frac{d}{dt} \text{scal}^{g+th} |_{t=0} = \Delta \text{tr } h + \delta(\delta h) - \sigma \text{tr } h.$$

and if h is TT,

$$\begin{aligned} D_g^2 \text{scal}(h, h) &= \frac{d^2}{dt^2} \text{scal}^{g+th} |_{t=0} \\ &= -\Delta(|h|^2) + \delta(\delta' h) - \frac{1}{2} \langle \Delta_E h, h \rangle + \sigma |h|^2. \end{aligned}$$

- Second divergence $P = \delta^2$ is an *underdetermined* elliptic operator.
↪ surjective but not injective principal symbol

- Second divergence $P = \delta^2$ is an *underdetermined* elliptic operator from trace-free symmetric 2-tensors to functions.
- $P^* = \overset{\circ}{\nabla}^2$ trace-free Hessian.

Thm (Delay)

For (M, g) , assume kernel of P^* are only constants.

Then for any compactly supported f with $\int_{\Omega} f \, dV = 0$, there is a compactly supported trace-free two-tensor U solving

$$\delta(\delta U) = f.$$

- Assumption is equivalent to (M, g) not a warped product.

Proof: constructing compactly supported perturbations

- Proof step 1: Construct solution to 2nd order.
- Set $g_t := g + th + \frac{t^2}{2}k$ with given h , find k !
- Since h is TT:

$$\frac{d}{dt} \text{scal}^{g_t} |_{t=0} = D_g \text{scal}(h) = 0$$

$$\frac{d}{dt} dV^{g_t} |_{t=0} = D_g dV(h) = \left(\frac{1}{2} \text{tr}_g h \right) dV^g = 0$$

- Solve for k such that

$$\frac{d^2}{dt^2} \text{scal}^{g_t} |_{t=0} = D_g \text{scal}(k) + D_g^2 \text{scal}(h, h) = f_0,$$

$$\frac{d^2}{dt^2} dV^{g_t} |_{t=0} = D_g dV(k) + D_g^2 dV(h, h) = 0,$$

- trace-free part of k : scal equation, trace of k : dV equation...

- Set $k = \frac{1}{n}|h|^2 g + \dot{k}$ where $\text{tr } \dot{k} = 0$. Then

$$D_g dV(k) + D_g^2 dV(h, h) = \left(\frac{1}{2} \text{tr}^g k + \frac{1}{4} (\text{tr}^g h)^2 - \frac{1}{2} |h|_g^2 \right) dV^g = 0,$$

- For scalar curvature equation we have

$$D_g \text{scal}(k) + D_g^2 \text{scal}(h, h) = \delta \left(\delta' h - \frac{1}{n} d|h|^2 + \delta \dot{k} \right) - \frac{1}{2} \langle \Delta_E h, h \rangle = f_0.$$

or

$$\delta^2 \dot{k} = -\delta \left(\delta' h - \frac{1}{n} d|h|^2 \right) + \left(\frac{1}{2} \langle \Delta_E h, h \rangle + f_0 \right).$$

- Both terms integrate to zero, Delay's theorem gives solution $\dot{k} \dots$
- \Rightarrow

$$\text{scal}^{g_t} = \text{scal}^g + \frac{t^2}{2} f_t + O(t^3)$$

$$dV^{g_t} = dV^g + O(t^3)$$

- Proof step 2: Iteration to exact solution. Compare implicit function theorem.
- Set

$$g_t^{(i)} := g + h_t^{(i)} + \frac{1}{2}k_t^{(i)}$$

with $h_t^{(0)} := th$ and $k_t^{(0)} := t^2k$.

- Recursive formulas:

$$\begin{aligned} D_g \operatorname{scal}(k_t^{(i+1)} - k_t^{(i)}) + D_g^2 \operatorname{scal}(h_t^{(i+1)}, h_t^{(i+1)}) - D_g^2 \operatorname{scal}(h_t^{(i)}, h_t^{(i)}) \\ = \operatorname{scal}(g) + \frac{t^2}{2} f_t - \operatorname{scal}(g_t^{(i)}) \end{aligned}$$

and

$$\begin{aligned} D_g dV(k_t^{(i+1)} - k_t^{(i)}) + D_g^2 dV(h_t^{(i+1)}, h_t^{(i+1)}) - D_g^2 dV(h_t^{(i)}, h_t^{(i)}) \\ = dV(g) - dV(g_t^{(i)}) \end{aligned}$$

- Meaning of recursive formulas?
- Set

$$g_{t,s}^{(i)} := g + sh_t^{(i)} + \frac{s^2}{2} k_t^{(i)}.$$

Then

$$\frac{d}{ds} \text{scal}(g_{t,s}^{(i)})|_{s=0} = 0,$$

$$\frac{d^2}{ds^2} \text{scal}(g_{t,s}^{(i)})|_{s=0} = D_g \text{scal}(k_t^{(i)}) + D_g^2 \text{scal}(h_t^{(i)}, h_t^{(i)}).$$

- Taylor expansion in s :

$$\begin{aligned} \text{scal}(g_t^{(i)}) &= \text{scal}(g_{t,1}^{(i)}) \\ &= \text{scal}(g) + D_g \text{scal}(k_t^{(i)}) + D_g^2 \text{scal}(h_t^{(i)}, h_t^{(i)}) + S_t^{(i)} \end{aligned}$$

where $S_t^{(i)}$ is Taylor remainder term.

- scal recursion:

$$D_g \text{scal}(k_t^{(i+1)}) + D_g^2 \text{scal}(h_t^{(i+1)}, h_t^{(i+1)}) = \frac{t^2}{2} f_t - S_t^{(i)},$$

or

$$\text{scal}(g_t^{(i+1)}) = \text{scal}(g) + \frac{t^2}{2} f_t + S_t^{(i+1)} - S_t^{(i)},$$

- Similar for dV

$$\begin{aligned} dV(g_t^{(i)}) &= dV(g_{t,1}^{(i)}) \\ &= dV(g) + D_g dV(k_t^{(i)}) + D_g^2 dV(h_t^{(i)}, h_t^{(i)}) + V_t^{(i)} \end{aligned}$$

where $V_t^{(i)}$ is Taylor remainder term.

- dV recursion:

$$D_g dV(k_t^{(i+1)}) + D_g^2 dV(h_t^{(i+1)}, h_t^{(i+1)}) = -V_t^{(i)}$$

or

$$dV(g_t^{(i+1)}) = dV(g) + V_t^{(i+1)} - V_t^{(i)},$$

- Proof step 3: Solve for $h_t^{(i)}$, $k_t^{(i)}$ just as in step 1.
- Proof step 4: Prove contraction estimates

$$\begin{aligned} & \| (h_t^{(i+2)} - h_t^{(i+1)}) \| + \| k_t^{(i+2)} - k_t^{(i+1)} \| \\ & \leq \frac{1}{3} \left(\| (h_t^{(i+1)} - h_t^{(i)}) \| + \| k_t^{(i+1)} - k_t^{(i)} \| \right). \end{aligned}$$

for small $t \Rightarrow$ convergence.

- Proof step 5: Prove regularity of limit.

- We have proven one half of:

Thm 2 (D.-Kröncke)

Let (M, \hat{g}) be an open Einstein manifold which is not locally isometric to a warped product. Then the following are equivalent:

- (i) (M, \hat{g}) is linearly stable.
- (ii) Close to \hat{g} , there is no metric g with

$$g - \hat{g}|_{M \setminus K} \equiv 0, \quad \text{vol}(K, g) = \text{vol}(K, \hat{g})$$

for some compact set $K \subset M$ which additionally satisfies

$$\text{scal}^g \geq \text{scal}^{\hat{g}} \quad \text{scal}^g(p) > \text{scal}^{\hat{g}}(p) \text{ for some } p \in M.$$

- + Neumann eigenvalue condition for $\Delta^{\hat{g}}$ in case $\text{scal}^{\hat{g}} > 0$.
- also equivalent: If g is close to \hat{g} with $\text{scal}^g \equiv \text{scal}^{\hat{g}}$ and

$$g - \hat{g}|_{M \setminus K} \equiv 0, \quad \text{vol}(K, g) = \text{vol}(K, \hat{g}),$$

then g is isometric to \hat{g} .

Proof: a generalized λ -functional

- Prove opposite implication in Theorem. Not a deformation argument!
- For (M, \hat{g}) and $\alpha > 0$, define

$$F_\alpha : \mathcal{M}_{\hat{g}}^\infty \times C^\infty(M) \rightarrow \mathbb{R}, \quad F_\alpha(g, f) := \int_M (\text{scal} + \alpha |\nabla f|^2) e^{-f} dV,$$

and

$$\lambda_\alpha(g) := \inf \left\{ F_\alpha(g, f) \mid f \in C^\infty(M), \int_M e^{-f} dV = 1 \right\}.$$

- $\alpha = 1 \Rightarrow$ Perelman λ -functional.
- α needed to handle boundary with auxiliary function satisfying a Laplace equation.
- substitution $\omega = e^{-\frac{f}{2}}$ gives

$$\lambda_\alpha(g) = \inf \left\{ G_\alpha(g, \omega) \mid \omega \in C^\infty(M), \int_M \omega^2 dV = 1 \right\}$$

where

$$G(g, \omega) := \int_M (4\alpha |\nabla \omega|^2 + \text{scal} \omega^2) dV.$$

- $\text{scal} \geq c$ implies $\lambda_\alpha(g) \geq c$, and if $\text{scal} \neq c$, then $\lambda_\alpha(g) > c$.

- First variation formula

$$D_g \lambda_\alpha(h) = - \int_M \langle \text{Ric} + \nabla^2 f - (\alpha - 1) \nabla f \otimes \nabla f, h \rangle e^{-f} dV \\ + \int_M \langle \frac{1}{2} (1 - \frac{1}{\alpha}) (\text{scal} - \lambda_\alpha(g)) g + \frac{1}{2} (\alpha - 1) |\nabla f|^2 g, h \rangle e^{-f} dV.$$

- First variation formula for g Einstein, $\text{Ric} = \sigma g$,

$$D_g \lambda_\alpha(h) = - \frac{\sigma}{\text{vol}(M, g)} \int_M \text{tr } h dV$$

- Einstein metrics are critical w.r.t. volume-preserving deformations, Ricci-flat metrics are critical for general deformations.

- Second variation formula (volume preserving h)

$$\begin{aligned}
 D_g^2 \lambda_\alpha(h, h) = & -\frac{1}{\text{vol}(M, g)} \int_M \left\langle \frac{1}{2} \Delta_E h - \delta^*(\delta h) - \frac{1}{2} \delta(\delta h) g, h \right\rangle dV \\
 & - \frac{1}{\text{vol}(M, g)} \int_M v \delta(\delta h) dV \\
 & + \frac{1}{\text{vol}(M, g)} \int_M ((\alpha - 1) \Delta v + \sigma v) \text{tr } h dV,
 \end{aligned}$$

where v solves

$$2\alpha \Delta v = \Delta(\text{tr } h) + \delta(\delta h) - \sigma \text{tr } h, \quad \nabla_\nu v = 0.$$

- Second variation formula for g Einstein, $\text{Ric} = \sigma g$, $h \in C_c^\infty(TT)$,

$$D_g^2 \lambda_\alpha(h, h) = -\frac{1}{2 \text{vol}(g)} \int_M \langle \Delta_E h, h \rangle dV.$$

- $\Rightarrow g$ should be local maximum of λ_α if g is stable.

- $\mathcal{M}_{\hat{g}}^\infty$ be the set of metrics on M such that $g - \hat{g}$ vanishes to every order at ∂M
- Study $D_{\hat{g}}^2 \lambda_\alpha(h, h)$ on

$$C_{c,0}^\infty(M)\hat{g} \oplus \delta^*(C_c^\infty(T^*M)) \oplus C_c^\infty(TT)$$

(volume preserving h) for \hat{g} stable Einstein. Exponentiate:

- Thm: If (M, \hat{g}) is stable Einstein, then there is a neighbourhood \mathcal{V} of \hat{g} in $\mathcal{M}_{\hat{g}}^\infty$ such that

$$\lambda_\alpha(g) \leq \lambda_\alpha(\hat{g})$$

for every $g \in \mathcal{V}$ with $\text{vol}(M, g) = \text{vol}(M, \hat{g})$. Further, equality holds if and only if g is Einstein.

- Thm 2 follows.

Application

- \Rightarrow The Riemannian Schwarzschild metric and the Taub-Bolt metric have compactly supported positive scalar curvature perturbations.
- conformal change to $\text{scal} = 0 \Rightarrow$ perturbation decreasing “mass” while length of circle at infinity is constant.

- Thank you for your attention!